

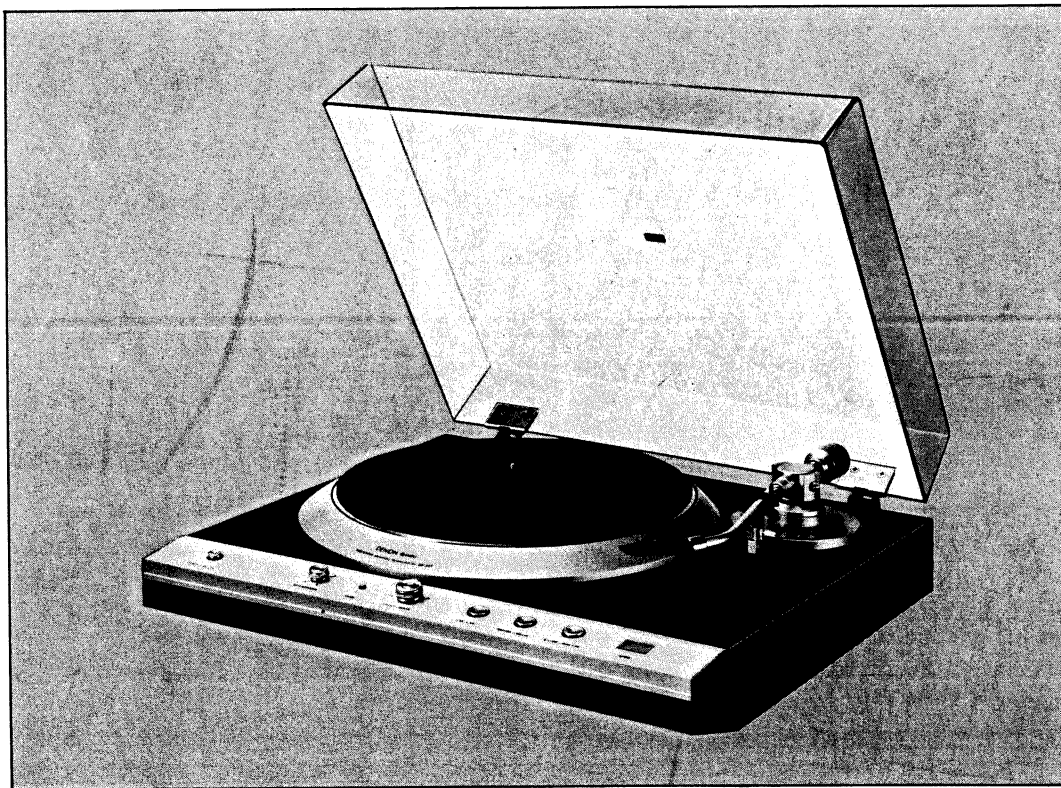
DENON

Hi-Fi Component Record Player

SERVICE MANUAL

SERVO-CONTROLLED DIRECT DRIVE AUTOMATIC RECORD PLAYER

MODEL DP-40F SERIES



Model DP-40F

NIPPON COLUMBIA CO., LTD.

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SAFETY PRECAUTIONS

Model DP-40F is designed and manufactured with careful consideration about product safety. For continued production safety, read following precautions and practice proper servicing.

1. Since the printed circuit board of 120V version of Model DP-40F have high voltage potential from the metal chassis regardless of the polarity of the AC supply, use an isolating transformer (1:1) for servicing.
2. Replace always with correct parts having correct rating, shape and material, etc. Especially the component with shading and ⚠ mark must be replaced only by the specified component for safety reasons.
3. For setting up the record player;
 - A) Do not damage the power cord by placing a heavy object on it, or by pinching it between angular objects. Do not fix the power cord by nails, etc. on wall.
 - B) Make sure any metal objects such as needle, hair pin or coin are not remaining inside the appliance.
 - C) Give sufficient clearance for ventilation holes at bottom. Allow more than 10cm clearance between the rear of cabinet and wall.

THEORY OF OPERATION

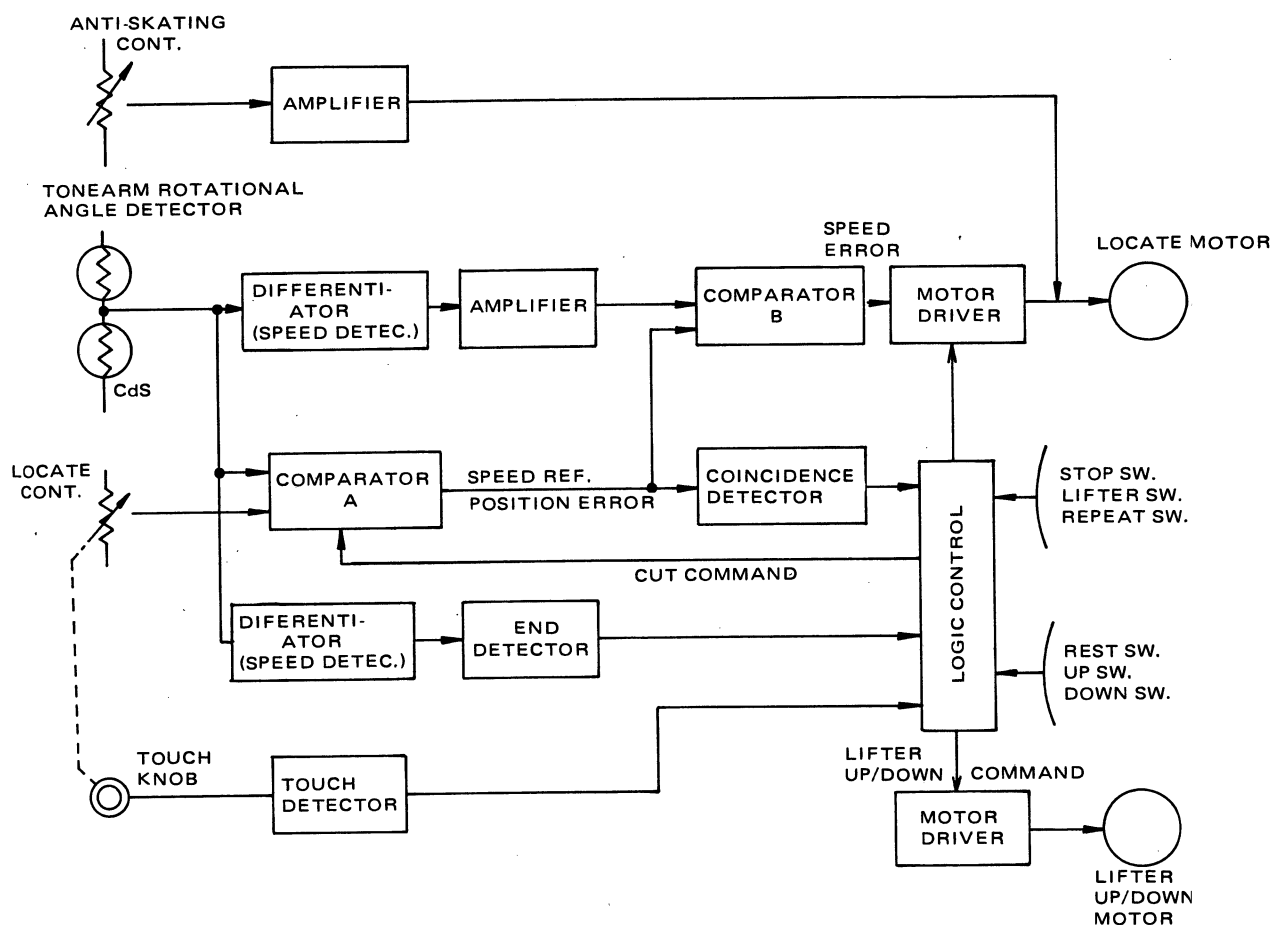


Fig. 1 Block diagram of tonearm control of DP-40F

Control of Auto-arm Motion

Block diagram of tonearm control circuit is shown in Fig. 1. As shown therein, the auto-arm control functions in accordance with various signals from the logic circuit defined by the functional state of the tonearm and the selection of operational mode.

In this chapter, the principle of servo control of tonearm is mainly explained. Assumption is made that the locate knob has been set to a position within 30cm diam. of a record. When the locate knob (being a touch sensor) is touched by hand, Comparator A compares the tonearm position signal and the preset locate signal. At this time, the comparator judges if the tonearm is inside of the preset position or outside of it. The output is a speed reference signal for moving the tonearm outward or inward depending on whether the tonearm is inside or outside of the preset position respectively.

Comparator B compares this speed reference signal with the signal proportional to the rotational speed of tonearm as a result of differentiating the tonearm position signal, or the detected speed signal. If this detected speed signal becomes over or under the speed reference signal, a speed error signal is generated at the output for feeding into the motor driver. Thus the servo loop functions so as to maintain a constant speed of tonarm.

As the tonarm reaches the preset locate position, the output of Comparator A becomes zero, ie, the speed reference signal becomes zero. (Since the positional error signal is zero, it means the tonearm position coincides the preset

position by the locate knob.) Accordingly, the rotation of tonearm rapidly decreases and finally stops, resulting in zero output of the speed signal. The positional servo control is thus accomplished to define the tonearm position. If the locate knob is turned again, the preset position is shifted. The tonearm moves again toward the newly ordered position.

If the locate knob is touched by hand during playback, the tonearm is lifted, and is returned to the preset locate position by command of the logic circuit. This function enables partial repeat of same music (desired band) as many times as touched. The servo controlled non-contact type Auto-arm mechanism has an extremely unique feature for such a new way of utilization.

Tonearm Drive Motor and Lifter Drive Motor

The locate motor affixed on the tonearm pivot consists of a coil as rotor and a magnet as stator. The reason is explained below:

If inversely, the coil is for the rotor and the magnet for the stator, there will be various drawbacks. That is; there are ferrous plates and levers near the magnet introducing irregular force on the tonearm pivot. In an extreme case, the tonearm may be turned, or not as severe as that, but horizontal sensitivity of tonearm will be impaired. Anyway, irregularity is so great that the anti-skating compensation would be out of question; furthermore, as the magnet rotates, the magnetic flux flows across the output signal leads of cartridge, possibly resulting in a voltage generation

of noise.

To solve these problems, the DENON Auto-arm has the construction described before. Full performance of high sensitivity tonearm without deteriorating S/N ratio is thus assured.

The exclusive arm lifter motor has a rotor magnet and a stator coil since it causes no problem.

Main Blocks of Circuit

1. Memory circuits

Two memory circuits are provided for tonearm motion. One is for sustaining the locate signal (LCT signal) during locate motion (during the time the tonearm moves from start until preset position). The other memory circuit is to memorize signal (CUT signal) for ejecting automatic function at any moment and returning the tonearm to the arm rest. The former memory circuit is indicated as "LCT_{FF}" and the latter "CUT_{FF}" in the schematic diagram. Both of them consist of a flip-flop of cross-connected NAND gates as shown in Fig. 2. It is a set-reset flip-flop with Gate A for set and Gate B for reset.

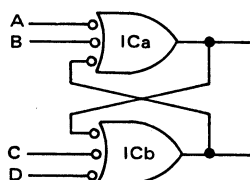


Fig. 2 Memory Flip-Flop

2. Coincidence detector of tonearm position

When the tonearm comes at the ordered position (at preset locate position or at arm rest) by servo control, 0V (Actually set to -0.3V because of offset voltage) is obtained at Pin ① of IC2. If the tonearm is outside of the ordered position, the tonearm is driven toward inside by the start signal. At this time, voltage at Pin ① of IC2 increases toward 0V from large negative voltage. If the tonearm is inside of the ordered position, it functions vice-versa. The coincidence detector is so arranged that it provides 0V only when the output of Pin ① of IC2 crosses 0V point. Other times whether for positive or negative inputs, only positive output is derived. See Fig. 3.

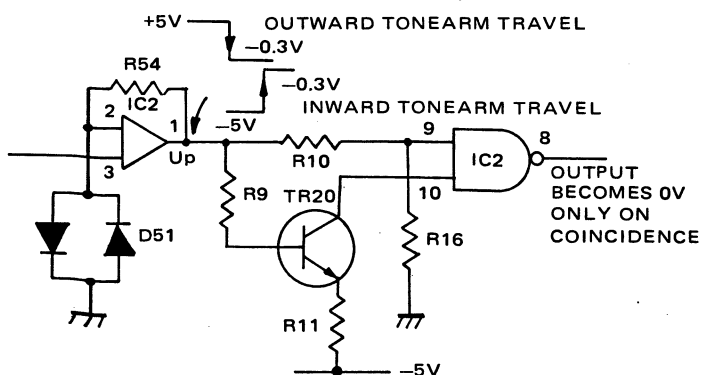


Fig. 3 Coincidence detector

3. Delay circuit for coincidence signal

The tonearm travel stops when it reaches the ordered position, either the preset locate position or the arm rest. As described earlier, when the tonearm reaches the above position, the coincidence signal is provided. Accordingly, Pin ⑪ of IC5 becomes high level which is in turn fed into Pin ⑩ of IC5 in Fig. 4. However, by TR3 and the capacitor C2 at its base, charging voltage (base voltage of TR3) gradually increases in a time determined by the time constant of the circuit. If the coincidence signal is sustained for a certain period of time, the emitter voltage of TR3 reaches high level and after that, a signal is obtained at Pin ⑧ of IC5 indicating that the tonearm position coincides the ordered position. By this signal, both memory circuits, LCT_{FF} and CUT_{FF} is simultaneously reset for descending the tonearm and the automatic function is completed.

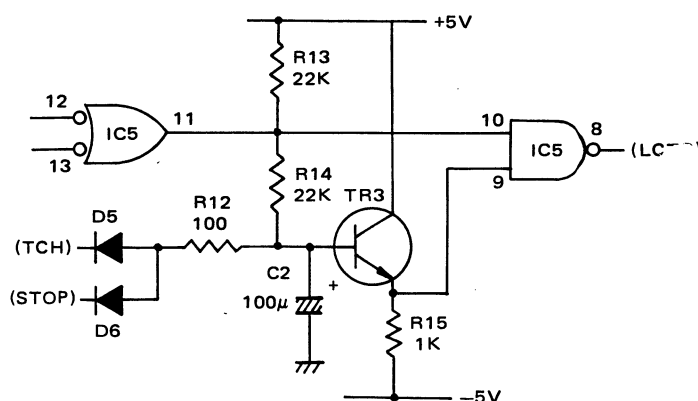


Fig. 4 Delay circuit for coincidence signal

ADJUSTMENT

Inside Mechanism Section

1. Micro switch position (up switch and down switch)

- 1-1. Remove the arm clasper at the arm rest.
- 1-2. Manually turn the white cam (15) in Fig. 8 counter-clockwise until it stops.
- 1-3. Adjust position of the up switch SW2 (with rolled actuator (16) in Fig. 8) so that the roller fits in the dent of the cam and the normally contact (N.C.) terminal makes contact with the common terminal.
- 1-4. Manually turn the white cam clockwise until it stops. (Make sure, at this time that the above rolled actuator of the up switch SW2 is pressed by the cam and the normally open (N.O.) terminal makes contact with the common terminal.)
- 1-5. In this state, adjust position of the down switch SW3 (21) in Fig. 8) so that its actuator is pressed and the N.O. terminal makes contact.
- 1-6. After the above adjustment, turn on the power and operate the lifter button and let the lifter motor up and down. Make sure that the N.C. terminal of up switch SW2 makes contact at lifted up position, and the N.O. terminal of down switch SW3 makes contact at down position.

2. Rest switch SW1 position

While the tonearm is returned to the arm rest, adjust the fixing position of the rest reed switch SW1 (3) in Fig. 8) to make contact.

Electrical Section

1. Offset adjustment (KU-318/KU-321)

- 1-1. Obtain zero balance of tonearm. Then, while touching the locate knob by hand, turn it to locate the tonearm to an optional position (about outside of 30cm).
- 1-2. Adjust VR1 so that the voltage at CN-5 (2) of TP-1 on the tonearm servo control P.W. board (KU-318/321) becomes $-0.3V$ when the tonearm stops (coincides the locate position). (Be sure to keep touching the locate knob during adjustment. The ground terminal is CN-5 (4) of TP-1.)

2. Record-end detection (KU-318/KU-321)

With the lifter button at up mode, set the stylus position at 60 mm radius from the center shaft and adjust VR2 so that the voltage at CN-5 (3) of TP-3 on the tonearm servo control P.W. board (KU-318/321) becomes $-3.5 \pm 0.2V$.

3. Locate knob position (KU-318/KU-321)

Insert the locate knob so that the dot comes at around the center of the VR. Turn the knob to align the dot with 30cm indication.

While touching the locate knob, adjust VR3 so that the stylus point comes on the lead-in position of 30cm LP record.

4. Phase adjustment of turntable control (KU-317/KU-320)

Connect the probe and ground of an oscilloscope to TP (3) and TP (1) of the turntable servo control P.W. board (KU-317/320) respectively.

Observe waveform and adjust VR1 for 33rpm and VR 2 for 45rpm so that the waveform becomes as shown in Fig. 5.

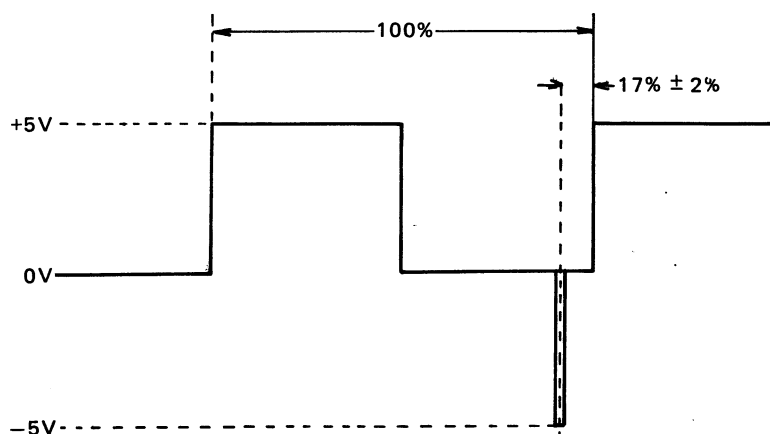


Fig. 5 Synchronized waveform

PARTS LIST FOR MODEL DP-40F SERIES

MAIN CONSTRUCTION

Ref. No.	Part No.	Part Name	Remarks	Ref. No.	Part No.	Part Name	Remarks
1	4218123005	RECORDED TURNTABLE		11	4418271003	C.B. BRACKET (A)	Black
	4118032306	MOTOR CHASSIS			1468076028	DUST COVER ASSY	
	1468065107	FRAME			FTS0701	HINGE PLATE	
2	△2339020209	POWER TRANS FMR 120V		11	1018101819	CABINET ASSY 120V	
	△2339023002	POWER TRANS FMR 200V ~ 240V			1018101822	CABINET ASSY 200V~240V	
	△2334029108	POWER TRANS FMR MULTI SPLY*			1018101835	CABINET ASSY 200V ~ 240V	
3	129801005	CUSHION RUBBER		11	1018101848	CABINET ASSY MULTI SPLY*	
4	4438156108	SPACER			1058032003	BOTTOM PLATE 120V	
5	△2178028404	MOTOR ASSY 200V~240V MULTI SPLY*			1058032016	BOTTOM PLATE 200V ~ 240V MULTI SPLY*	
6	△2178036108	MOTOR ASSY 120V		12	1058023203	F. BOTTOM PLATE	Metal
	3918423006	MAGNETIC HEAD			3158242005	SHELL ACCESSORY ASSY	
	△2129039002	PUSH (POWER) SWITCH 120V			FPU-555	HEAD SHELL UNIT	
7	△2124049055	PUSH (POWER) SWITCH 200V ~ 240V MULTI SPLY*	Surface Locate Anti-skate	13	KU-298	OPERATION PANEL UNIT	
	1038066002	PANEL ASSY			KU-317	MOTOR SERVO AMP UNIT 120V	
	1128038209	KNOB ASSY			KU-320	MOTOR SERVO AMP UNIT 200V~240V MULTI SPLY*	
8	4118040301	FRONT CHASSIS	STOP	14	KU-297	ARM DRIVE CONTROL	
9	4128031009	SUPPORTER			KU-318	ARM SERVO UNIT 120V	
10	3998014008	LED ASSY		15	KU-321	ARM SERVO UNIT 200V ~ 240V MULTI SPLY*	
	1138064001	PUSH BUTTON ASSY			PS-141	POWER SUPPLY UNIT 200V ~ 240V MULTI SPLY*	
	FPU-670	TONE ARM UNIT		17	2123315007	VOLTAGE SELECTOR MULTI SPLY*	
10	2039616007	OUT PUT CORD					
	4018006102	HINGE					
	FMD05241	INSULATOR					

Note: *MULTI SPLY: 110V ~ 240V Switchable

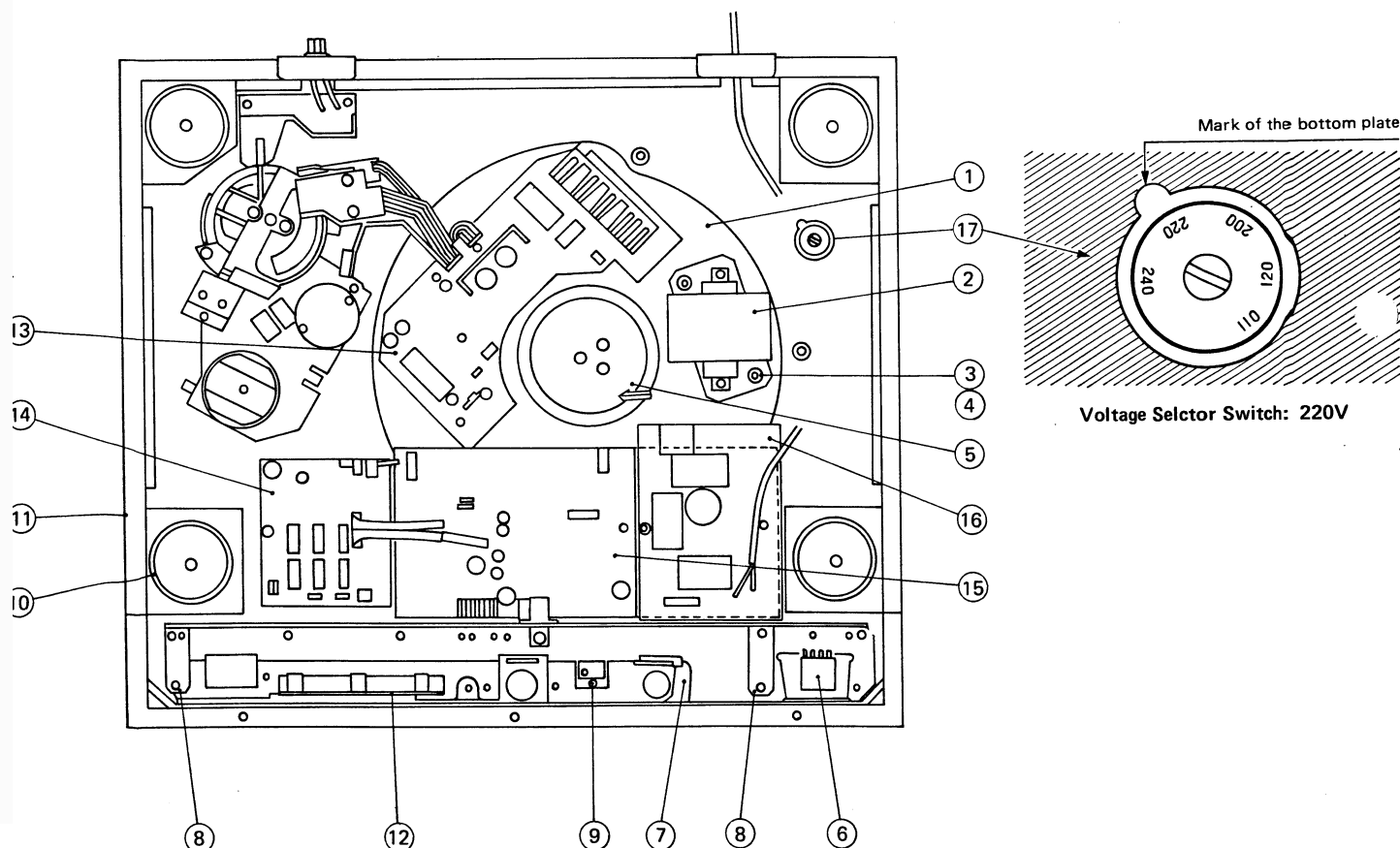


Fig. 6 BOTTOM VIEW
(BOTTOM PLATE REMOVED)

EXPLODED VIEW (of Tonearm)

Ref. No.	Part No.	Part Name	Remark
1~5	3158232002	MAIN BODY ASS	
2	3158248009	GUIDE PIN ASS	
3	3158236202	SHAFT CASE	
4		3×3 CPS	
5	4744200003	3×3 BSS(A)	(×4)
6	3158220001	BALANCE WEIGHT ASS	
7~17	3158223011	ARM BASE ASS	
8	3158226005	LIFTER ARM ASS	
9	3158066003	STOP SCREW	
10	3158225103	ARM REST ASS	
11	4638092004	LIFTER SPRING	
12	3158229002	LIFTER SHAFT	
13	4761003009	3E RING	
14	4751005004	4W	
15	3158066003	STOP SCREW	
16	4744207013	4×8 BSS(A)	
17	3158230004	COVER PLATE	
18	4418231108	SHIELD COVER BASE ASS	
19		3×8 BOLT	

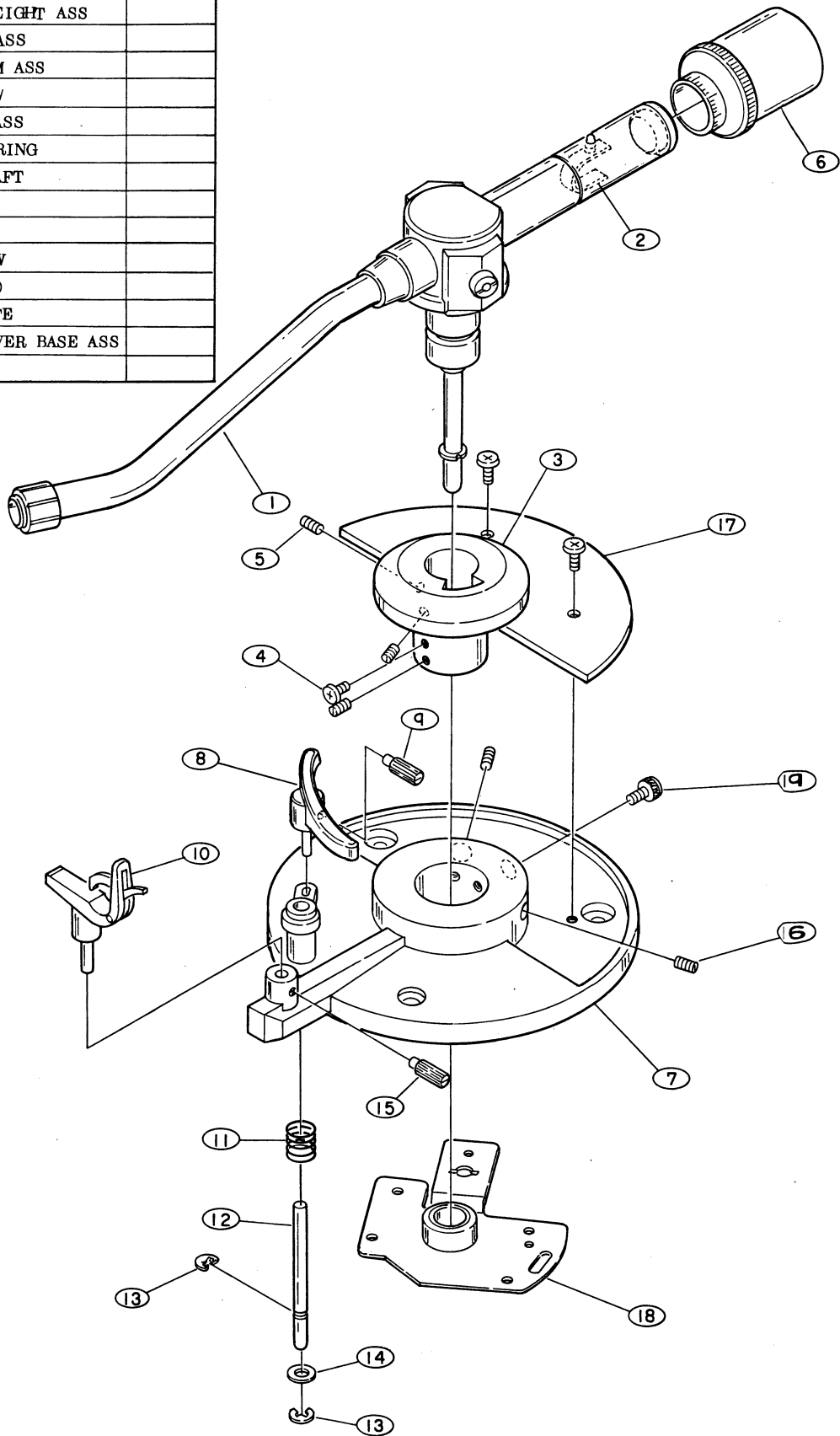


Fig. 7 TONEARM

EXPLODED VIEW (of Sensor)

Ref. No.	Part No.	Part Name	Remark	Ref. No.	Part No.	Part Name	Remark
1	2178030201	MOTOR (B)		21	2129053004	MICRO SWITCH	
2	4713303016	3×6 CRS		22	4418273108	SWITCH SUPPORTER	
3	2129018007	REED SWITCH		23	4498017300	POLARIZED PLATE(A)	
4	4700009006	3×6 CPSW		24	4338089100	SHUTTER	
5	4128032105	REED SW BRACKET		25	3410009108	MAGNET	
6	4730304014	3×8 CBRTS(1)		26	2178029403	MOTOR(A)	
7	4774003013	3×3 SS(A)		27	4148037407	SHIELD COVER	
8	4218121104	MOTOR ARM		28	4730308010	3×14 CBRTS(1)	
9	4761001001	2E-RING		29	2228107204	MOTOR SERVO PCB 06A	
10	4418220106	CONNECTION PLATE		30	4418271003	CB BRACKET	
11	4118030609	LIFTER CHASSIS ASS		31	4713304015	3×8 CBS	
12	4713104011	2×8 CRS		32	3939030009	CDS	
13	4761003009	3E-RING		33	4418229204	CDS HOLDER	
14	4770090058	WASHER		34	4498018105	POLARIZED PLATE(B)	
15	4248005407	SLIDER CAM		35	4712303017	3×6 CFS	
16	2129064006	MICRO SWITCH		36	4418228108	LED HOLDER	
17	4418221105	SWITCH BRACKET		37	3939023029	LED	
18	4318019608	DAMPER ASS		38	4730353010	3×6 CBRTS	
19	4218122307	DAMPER ARM		39	4148045004	SHUTTER COVER	
20	4713808005	23×10 CRS					

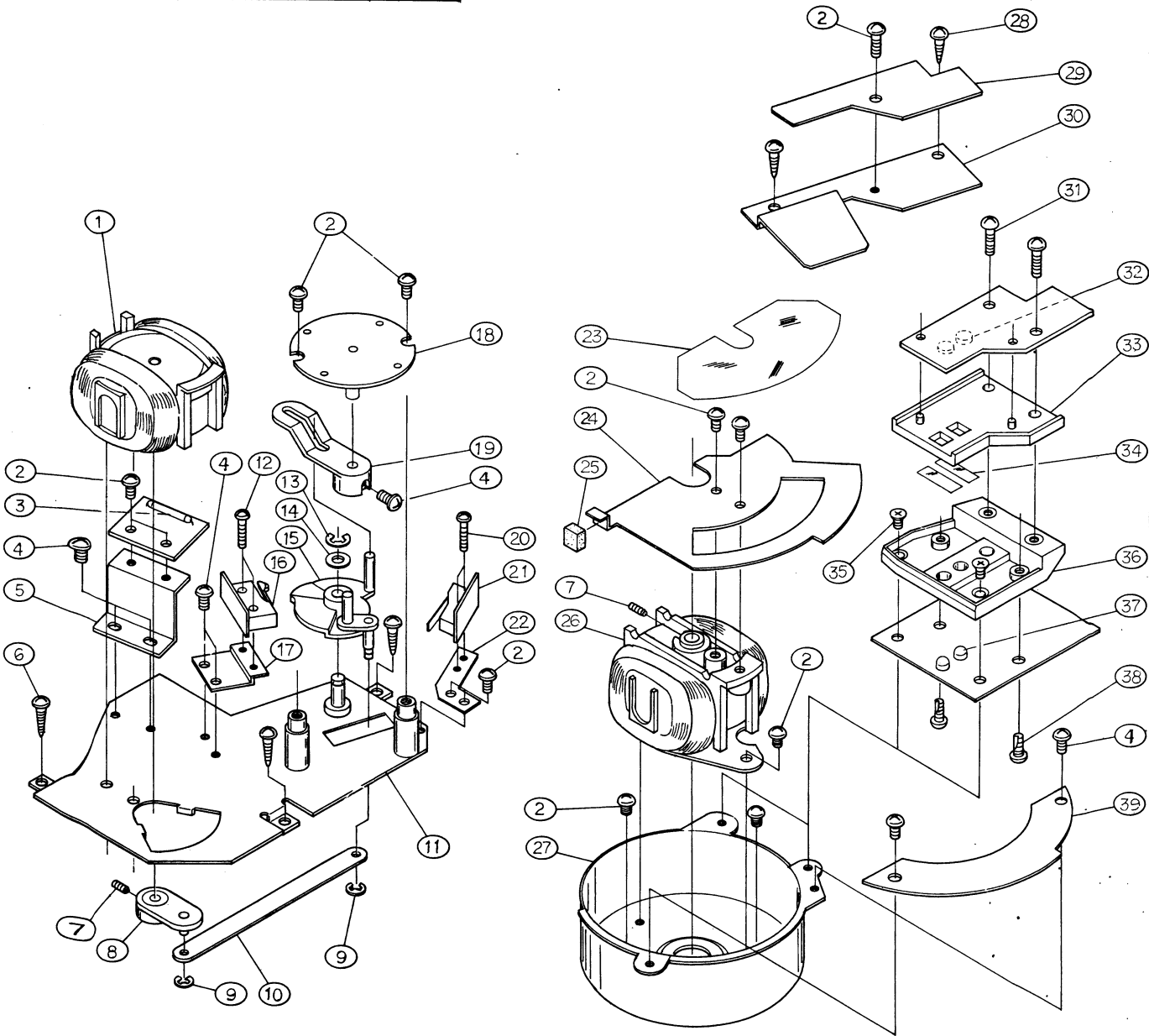
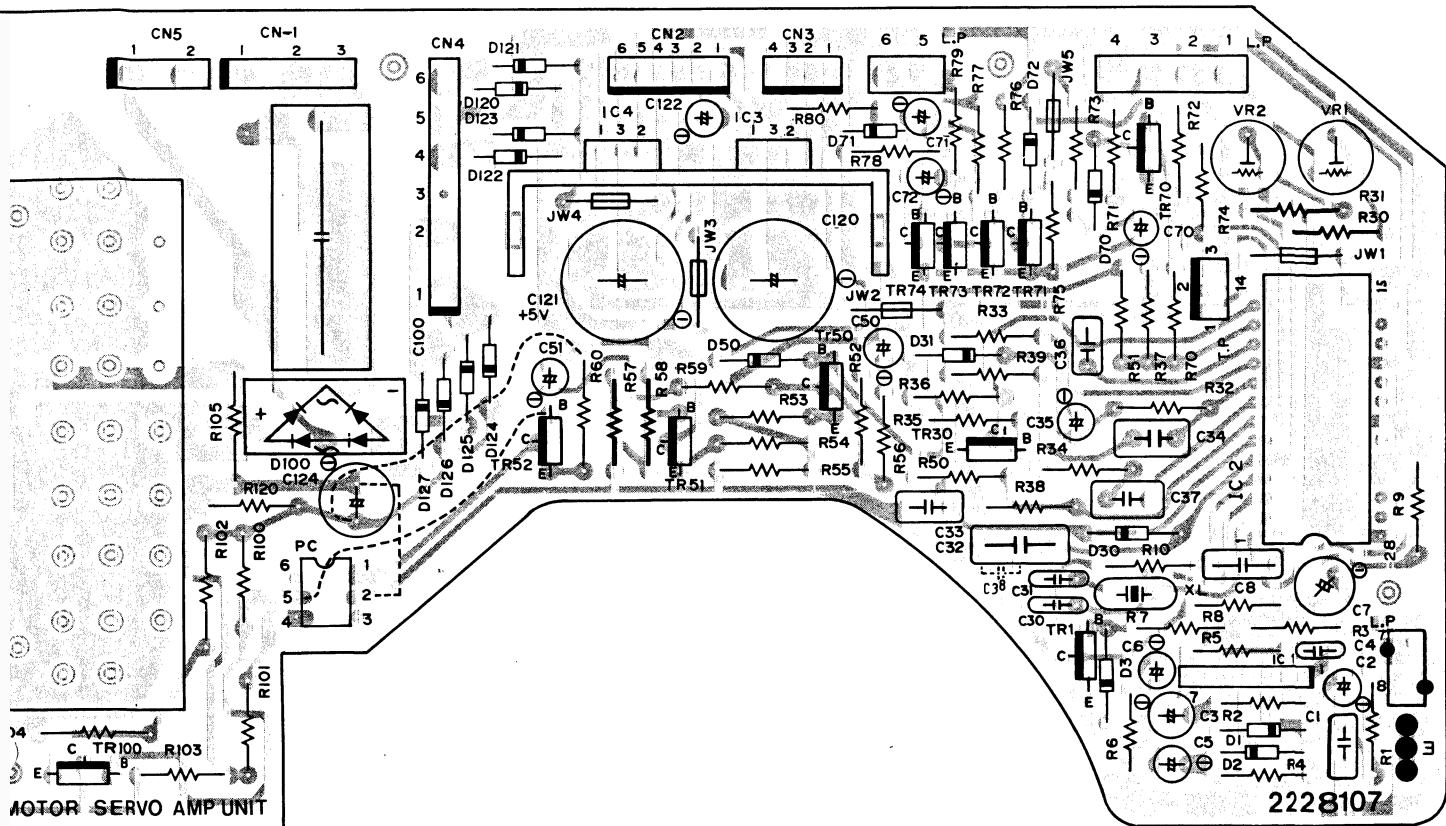
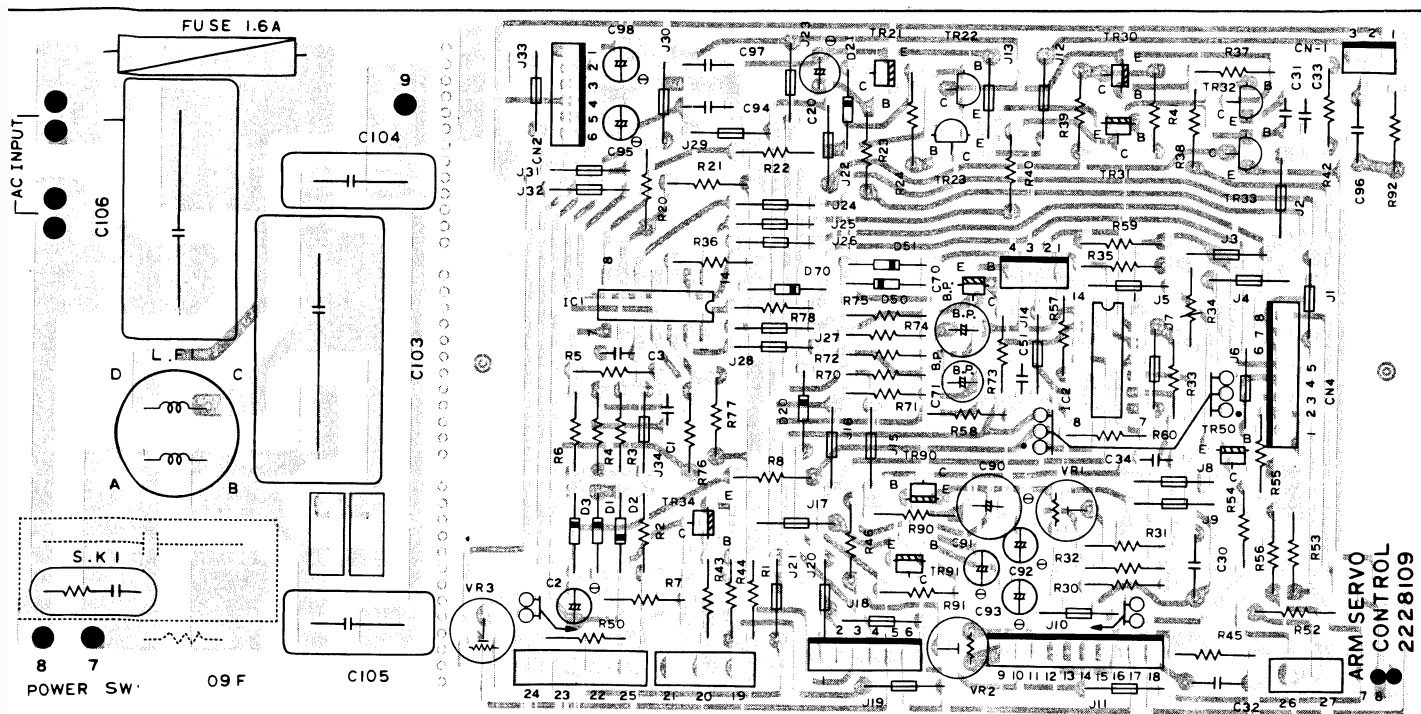


Fig. 8 SENSOR/ANGULAR CONTROL MOTORS



KU-317/KU-320 MOTOR AMP UNIT

Ref. No.	Part No.	Part Name	Remarks	Ref. No.	Part No.	Part Name	Remarks
SEMICONDUCTOR GROUP				CAPACITOR GROUP			
IC1	2630094028	TA7122BP (C)		C1	2551076002	CQ93M1H223K	0.022μF50V
IC2	2620075002	SC3120A		C2, 50	2544043000	CE04W1HR47=	0.47μF50V
IC3	2680009005	FS-7805M		C3	2544017007	CE04W1C470=	47μF16V
IC4	2680017000	FS-7905M		C4, 30, 31	2533619005	CC45SL1H470J	47pF5%50V
P.C.	3939027012	PC613 (G)		C5, 6, 35, 122	2544015009	CE04W1C100=	10μF16V
TR1, 30, 50	2730021030	2SC458 (C)		C7	2544010004	CE04W1A101=	100μF10V
51, 70, 71,	↑	↑		C8	2551066009	CQ93M1H332K	0.0033μF50V
72, 73, 74	↑	↑		C32	2551122011	CQ93M1H563J	0.056μF5%50V
TR52, 100	2710040028	2SA673 (C)		C33, 37	2551070008	CQ93M1H682K	0.0068μF50V
TR101	2730196017	2SC2023		C34	2551121038	CQ93M1H123J	0.012μF5%50V
D1, 2, 3, 30,	2760049008	1S2076		C36	2551062003	CQ93M1H152K	0.0015μF50V
50, 70, 71	↑	↑		R51, 70	2544023004	CE04W1E3R3=	3 3μF25V
D72	2760244007	MZ303A		C71*	2549009010	CE04W1H010MHS	1μF20%50V
D100	2760213009	1S2372A					Low leakage
D120, 121,	2760237001	RV06					Current
122, 123, 124,	↑	↑					10μF20%50V
125, 126, 127	↑	↑					Low leakage
RESISTOR GROUP							4μF200VAC
R1, 6, 8, 50	2410330009	RD14B2E472J	4.7KΩ1/4W				Metalized film
R2, 7, 76	2410354001	RD14B2E473J	47KΩ1/4W				1000μF16V
R3	2410362006	RD14B2E104J	100KΩ1/4W				470μF2%V
R4	2410378003	RD14B2E474J	470KΩ1/4W				100μF1%V
R5	2410308002	RD14B2E561J	560Ω1/4W	OTHER PARTS GROUP			
R9, 53, 54	2410290000	RD14B2E101J	100Ω1/4W		4178020413	HEAT SINK	
56, 60	↑	↑	↑		4178028004	HEAT SINK	
R10, 36	2410338001	RD14B2E103J	10KΩ1/4W		2618007008	CRYSTAL (9MHZ)	
R30*	FEP101110	RN1/4PS36KΩG	36KΩ2%1/4W		2035622008	3P MIN. CONNE.	
			Metal film			PIN. for Test Point	
R31*	FEP101127	RN1/4PS24KΩG	24KΩ2%1/4W		FEP12802	MINI. CONNE. PIN.	
			Metal film			ASSY for Motor	
R32	2410759004	RD14B2E564J	560KΩ1/4W				
R33, 80	2410334005	RD14B2E682J	6.8KΩ1/4W				
R34, 37, 120	2410326000	RD14B2E332J	3.3KΩ1/4W				
R35, 52, 75,	2410342000	RD14B2E153J	15KΩ1/4W				
79	↑	↑	↑				
R38, 55, 71	2410322004	RD14B2E222J	2.2KΩ1/4W				
R39	2410328008	RD14B2E392J	3.9KΩ1/4W				
R51, 78	2410366002	RD14B2E154J	150KΩ1/4W				
R57*	FEP101138	RN1/4PS8.2KΩG	8.2KΩ2%1/4W				
			Metal film				
R58*	FEP101122	RN1/4PS24KΩG	24KΩ2%1/4W				
			Metal film				
R59	2410314009	RD14B2E102J	100KΩ1/4W				
R70, 73, 74	2410346006	RD14B2E223J	22KΩ1/4W				
R72	2410372009	RD14B2E274J	270KΩ1/4W				
R77, 103	2410306004	RD14B2E471J	470Ω1/4W				
R100	2410304006	RD14B2E391J	390Ω1/4W				
R101	2410296004	RD14B2E181J	180Ω1/4W				
R102	2410161003	RD14B2H101J	100Ω1/4W				
R104	2410348004	RD14B2E272J	2.7KΩ1/4W				
R105	2440013024	RS14B3A4R7JNBF	4.7Ω1W				
			Metal oxide				
	EP-5462-14	SOLID VOLUME	(15KΩ)				
	EP-5462-15	SOLID VOLUME	(22KΩ)				



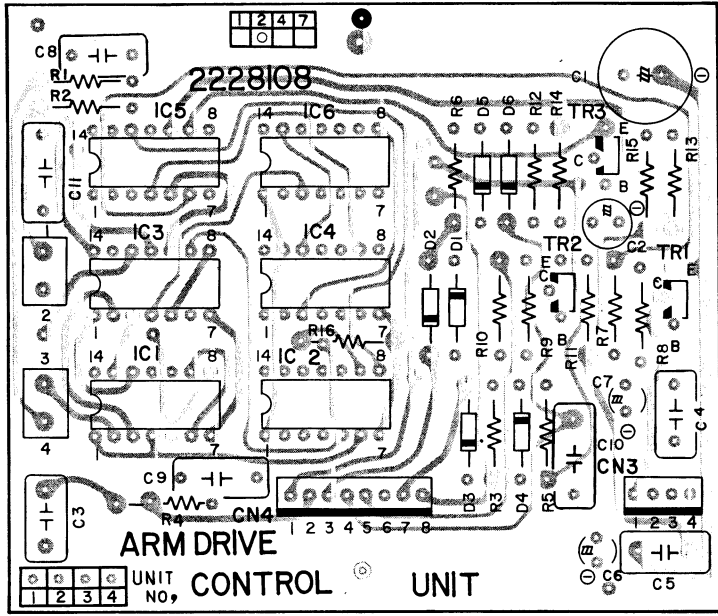
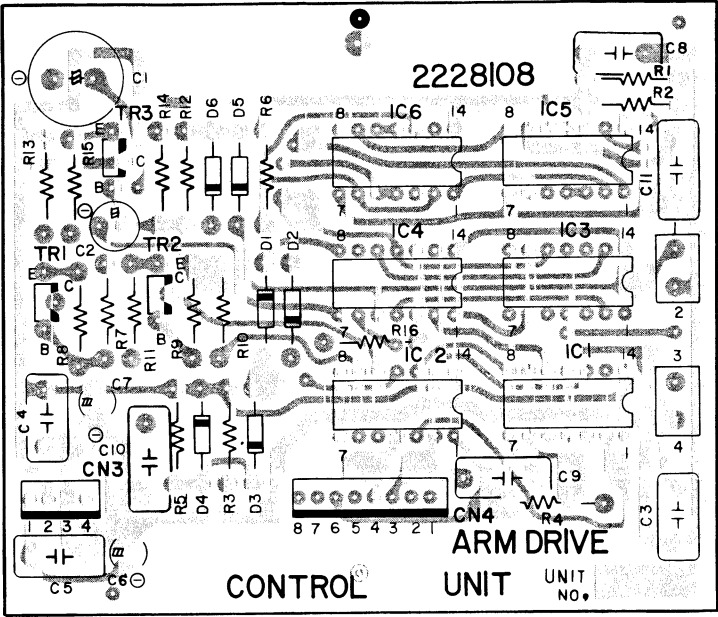
KU-318/KU-321 ARM SERVO CONTROL UNIT

Ref. No.	Part No.	Part Name	Remarks	Ref. No.	Part No.	Part Name	Remarks
SEMI CONDUCTOR GROUP				R70	241032008	RD14B2E392J	3.9K Ω 1/4W
IC1, IC2	2630075005	HA17902P		R71	2410334005	RD14B2E682J	6.8K Ω 1/4W
TR21, TR31, TR70, TR90	2730021030	2SC458 $\odot$		R75	2410370001	RD14B2E224J	220K Ω 1/4W
TR22, TR32	2740036002	2SD468 $\odot$		R77	2410298002	RD14B2E221J	220 Ω 1/4W
TR23, TR33	2720025004	2SB562 $\odot$		VR1	EP-546215	SOLID VOLUME	
TR30, TR50, TR91	2710040028	2SA673 $\odot$		VR2	EP-54621	SOLID VOLUME	
TR34	2740038000	2SD467 $\odot$		VR3	EP-546213	SOLID VOLUME	
D1 ~ 3	2760049008	1S2076		CAPACITOR GROUP			
D20, D21	27600216019	KB265		C1	2551066009	CQ93M1H332K	0.0033 μ F 50V
D50, D51	2760241000	MZ305B or HZ5B		C2	2544054002	CE04W1C220=	22 μ F 16V
D70				C3	2531021006	CK45F1M102	100pF 50V
RESISTOR GROUP				C20	2544005006	CE04W0J331=	330 μ F 6.3V
R1	2410316007	RD14B2E122J	1.2K Ω 1/4W	C31	2551072006	CQ93M1H103K	0.01 μ F 50V
R2, R50, R52	2410332007	RD14B2E562J	5.6K Ω 1/4W	C32, C96	2531027000	CK45F1H104Z	0.1 μ F 50V
R3	2410358007	RD14B2E683J	68K Ω 1/4W	C34	2533637003	CC45SL1H271	270pF 50V
R4, R56, R76	2410330009	RD14B2E472J	4.7K Ω 1/4W	C35	2533633007	CC45SL1H181	180pF 50V
R5, R33	2410765001	RD14B2E105J	1M Ω 1/4W	C51	2533657009	CC45SL1H101K	100pF 50V
R6, R41	2410306004	RD14B2E471J	470 Ω 1/4W	C70, C71	2543014027	CE04D1C100BP	10 μ F 16V Bipolar
R7, R20, R23, R34, R36, R73	2410338001	RD14B2E103J	10K Ω 1/4W	C90	2544006005	CE04W0J471=	470 μ F 6.3V
R8, R43, R59, R90	2410314009	RD14B2E102J	1K Ω 1/4W	C91	2544010004	CE04W1A101=	100 μ F 10V
R21, R78	2410322004	RD14B2E222J	2.2K Ω 1/4W	C92, C93	2544044009	CE04W1H010=	1 μ F 50V
R22, R40	2410302008	RD14B2E331J	330 Ω 1/4W	C94	2531026001	CK45F1H473Z	47000pF 50V
R24	2440020020	RS14B3A180JNBF	18 Ω 1W	C95	2544015009	CE04W1C100=	10 μ F 16V
R30	2410763003	RD14B2E824J	820K Ω 1/4W	OTHER PARTS GROUP			
R31	2410352003	RD14B2E393J	39K Ω 1/4W	CDS1, CDS2	3939030009	CDS	
R32	2410320006	RD14B2E182J	1.8K Ω 1/4W	LED1, LED2	3939023929	LED (SEL101S)	
R35	2410348004	RD14B2E273J	27K Ω 1/4W	SW1	2129018007	REED SWITCH	
R37, R38, R72, R91	2410346006	RD14B2E223J	22K Ω 1/4W	SW2	2129090009	MICRO SWITCH	
R39, R54	2410342000	RD14B2E153J	15K Ω 1/4W	SW3	2129053004	MICRO SWITCH	
R42, R57	2410362006	RD14B2E104J	100K Ω 1/4W	120V MODELS (KU-318) ONLY			
R44	2410288009	RD14B2E820J	82 Ω 1/4W	R100	2410292008	RD14B2E121J	120 Ω 1/4W
R45, R92	2410290000	RD14B2E101J	100 Ω 1/4W	C103, C106	2568017012	CF99B2BAC104MW	0.1 μ F 125VAC
R46	2410286001	RD14B2E680J	68 Ω 1/4W	C104, C105	2568017019	CF99B2BAC102MW	0.001 μ F 125VAC
R55	2410354001	RD14B2E473J	47K Ω 1/4W	SK1	FEP-429H	SPARK KILLER	
R58	2410374007	RD14B2E334J	330K Ω 1/4W	F100	2398001007	LINE FILTER COIL	
					2061018039	FUSE	(1.6A 250V)

WARNING:

Components with Δ marks and shading have special characteristics important to safety.

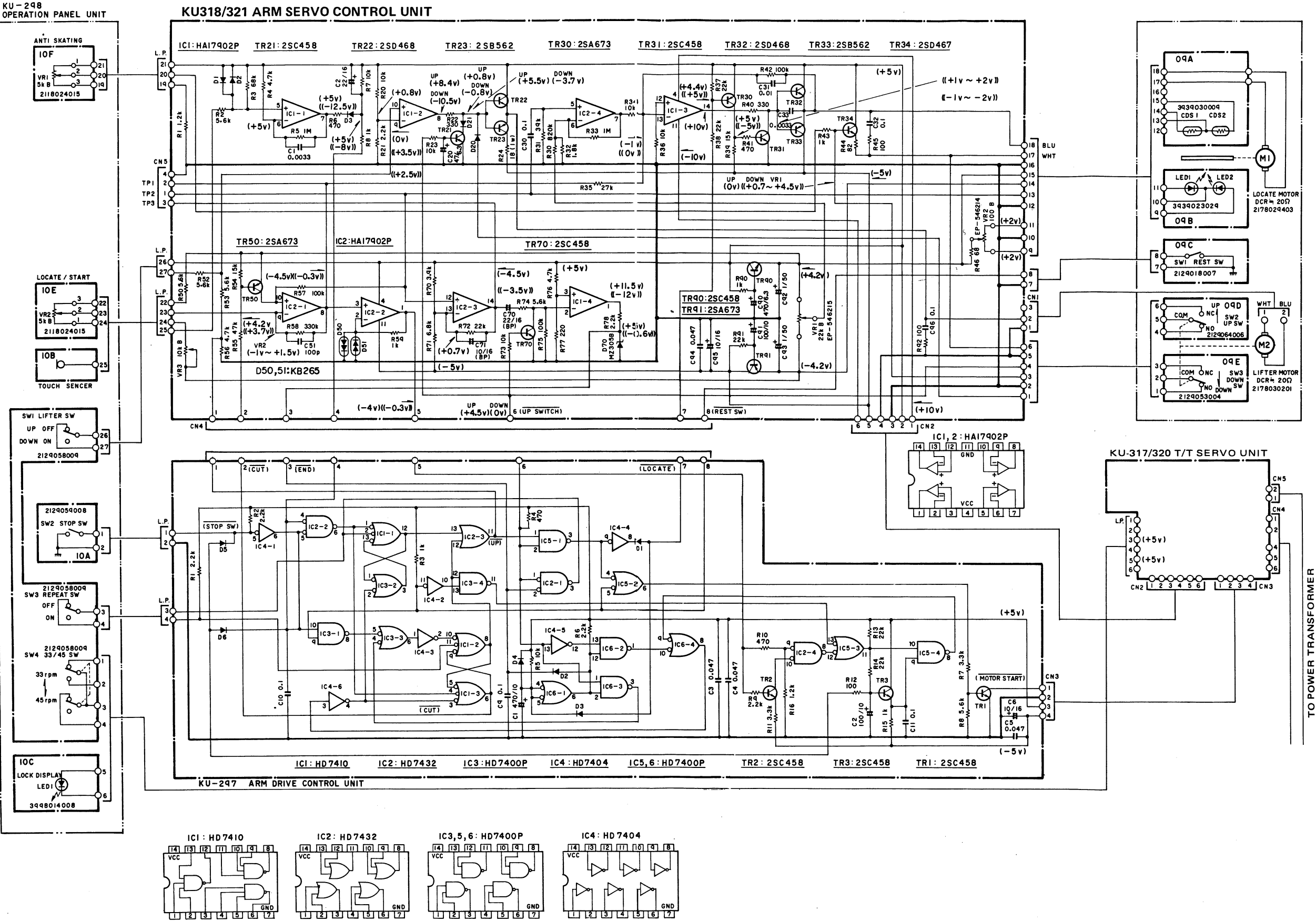
They must be replaced only by specified components.



KU-297 ARM DRIVE CONTROL UNIT

Ref. No.	Part No.	Part Name	Remarks
SEMI CONDUCTOR GROUP			
IC1	2620076001	HD7410	
IC2	2620082008	HD7432	
IC3, 5, 6	2620056005	HD7400P	
IC4	2620080000	HD7404	
TR1, 2, 3	2730021030	2SC458 (C)	
D1 ~ 6	2760049008	1S2076	
RESISTOR GROUP			
R1, 2, 6, 9	2410322004	RD14B2E222J	2.2K Ω /4W
R3, 15	2410314009	RD14B2E102J	1K Ω /4W
R4, 10	2410306004	RD14B2E471J	470 Ω /4W
R5	2410338001	RD14B2E103J	10K Ω /4W
R7, 11	2410326000	RD14B2E332J	33K Ω /4W
R8	2410332007	RD14B2E562J	5.6K Ω /4W
R12	2410290000	RD14B2E101J	100 Ω /4W
R13, 14	2410346006	RD14B2E223J	22K Ω /4W
R16	241316007	RD14B2E122J	1.2K Ω /4W
CAPACITOR GROUP			
C1	2544006005	CE04W0J471	470 μ F6.3V
C2	2544010004	CE04W1A101	100 μ F10V
C3, 4, 5	2531026001	CK45F1H473Z	0.047 μ F50V
C6	2544015009	CE04W1C100	10 μ F16V
C9, 10, 11	2531027000	CK45F1H104Z	0.1 μ F50V

SCHEMATIC DIAGRAM OF TONEARM SERVO CONTROL OF MODEL DP-40F



NOTES: • ALL RESISTORS ARE IN OHMS AND 1/4W UNLESS OTHERWISE SPECIFIED.
• CAPACITORS ARE IN μ F WITH NO UNIT, AND pF WITH P.
• VOLTAGES IN () ARE AT STAND-BY AND () ARE AT FUNCTION.
MEASURED WITH VOLTMETER (DC 100k Ω /V).
• ALL DIODES UNLESS OTHERWISE SPECIFIED ARE IS2076
• L.P. INDICATES WIRE WRAPPING CONNECTIONS.

• Δ COMPONENTS WITH Δ MARKS AND SHADING HAVE SPECIAL CHARACTERISTICS IMPORTANT TO SAFETY. THEY MUST BE REPLACED ONLY BY SPECIFIED COMPONENTS.
* SCHEMATIC DIAGRAM SHOWS A BASIC CIRCUIT. IT IS SUBJECT TO MODIFICATION FOR IMPROVEMENT.



SPECIFICATION

PHONO MOTOR

Drive system:	Direct drive by AC servo motor
Speeds:	33-1/3 rpm and 45 rpm
Wow/Flutter:	0.015% wrms*
S/N ratio:	More than 75 dB (DIN-B)
Rise time:	Less than 2.0 sec. to reach 33-1/3 rpm.
Platter:	Casted aluminum, 300 mm diam.
Motor:	AC servo motor
Speed control system:	Speed servo control by frequency detection system combined with phase control system with reference to the quartz crystal oscillator
Load infection:	0% (At out-most groove with stylus force of 80 g)
Speed deviation:	Less than 0.002%

TONARM

Type:	S-shaped, static balance type with damping system
Automatic mechanism:	Electronically servo controlled
Effective length:	244 mm
Stylus force range:	0—2.5 g/rotation, 0.1 g direct reading
Acceptable weight of cartridge:	15 g—21 g (including shell)
Head shell:	Impact molded rigid light metal, 9 g (net)
Output cord:	Low capacitance cord

GENERAL

Power supply:	Rated voltage and frequency are shown on rating label at back of cabinet and/or the label attached to the AC cord.
Power consumption:	18 W
Dimensions:	485(W) x 447(D) x 146(H) (mm), dust cover closed
Weight:	Approx. 12.5 Kg
	* Measured by DENON's method using magnetic pulse wheel.
	** Above specifications are subject to alteration without notice.

Dimensions (mm)

